CHAPTER 04: GALERKIN METHOD

GENERAL EXPRESSION OF GALERKIN METHOD

Let's write down Eq.03-4 again.

$$
\int_{\Omega} W_A \left(u - \phi \right) \, d\Omega = \sum_{A=1}^n a_A \int_{\Omega} W_B N_A \, d\Omega
$$
 \n \dots

Galerkin Method uses a derivative of approximate function \hat{u} with respect to unknown coefficient a, as the **weighing function** W. This means,

$$
W=\frac{\partial}{\partial a}\hat{u}
$$

Because $\hat{u} = \varphi + \sum_{A=1}^{n}$ $\hat{\mathsf{u}} = \varphi + \sum_{A=1} a_A \mathsf{N}_A$ (from Eq.03-1), the W_A (W that corresponds to a specific node "A") can be written as follows:

$$
W_{A} = \frac{\partial}{\partial a_{A}} a_{A} N_{A} = N_{A}
$$

Therefore,

WA = NA ..Eq.04-2

In shorts, **Galerkin Method** uses N (**shape function**) for W (**weighting function**).

Inserting Eq.04-2 into Eq.04-1, then,

$$
\int_{\Omega} N_A \left(u - \phi \right) \hspace{-2pt} d \Omega = \sum_{A=1}^n a_A \int_{\Omega} N_A N_B \hspace{-2pt} \, d \Omega \; \ldots \hspace{-2pt} \ldots \hspace
$$

The term $\sum_{A=1}^{n}$ $\sum_{\mathsf{A}=\mathsf{1}}\mathsf{a}_{\mathsf{A}}$ is a vector form and can be expressed as \mathbf{I} \mathbf{I} J $\overline{}$ $\left\{ \right.$ \mathbf{I} \mathbf{I} \mathbf{I} \mathfrak{r} $\overline{}$ ₹ \int n 2 1 a a a $\left.\frac{a}{b}\right\}$ and called **displacement vector**, or d .

The term $\int_{\Omega} N_A N_B d\Omega$ forms n x n matrix form and expressed as K_{AB}. This is called **stiffness matrix**.

Finally, the LHS term is called **force vector** and expressed as f .

Therefore, Eq.04-3 can be shown as:

$$
\bar{f} = K_{AB} \bar{d}
$$
, or simply f=Kd.

$$
\underbrace{\int_{\Omega} N_{A}(u - \varphi) d\Omega}_{\overline{f}} = \underbrace{\sum_{A=1}^{n} a_{A} \int_{\Omega} N_{A} N_{B} d\Omega}_{\overline{d}}
$$

LEAST SQUARE METHOD (OFF THE TOPIC)

Galerkin Method is one of methods among **Method of Weighted Residual**. What if we choose something else for the weighing function W?

Suppose we choose the derivative of residual R with respect to unknown coefficient a as weighing function.

That is,

$$
W_{_A}=\frac{\partial}{\partial a_{_A}}R
$$

The LH side of Eq.03-3 becomes

$$
\int_{\Omega}\!\!R Wd\Omega=\int_{\Omega}R\,\frac{\partial}{\partial a_{_A}}Rd\Omega
$$

By the way, if we want to achieve a minimum of the integral of squared R, so-called **Least Square Method**

$$
\int_\Omega\!\!R^2d\Omega=0
$$

Comparing this equation with Eq.03-3, we can say that **Least Square Method** is one of the **Method of Weighted Residual** in which the derivative of residual R with respect to unknown coefficient is chosen as weighing function.

> **Least Square Method** is *not* FEM to solve structural engineering problem.